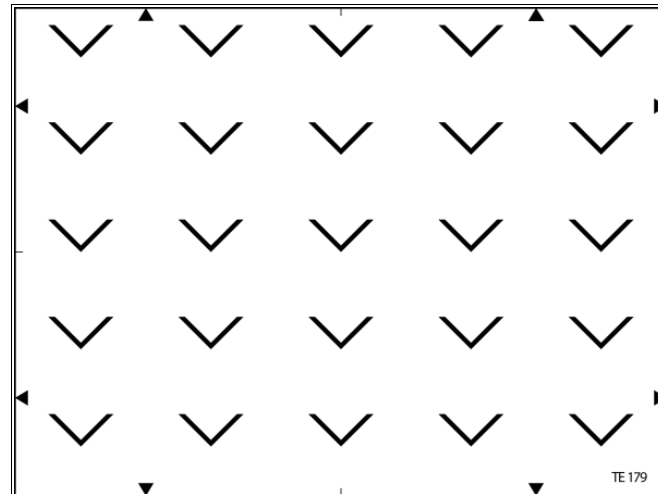




# REGISTRATION TEST CHART

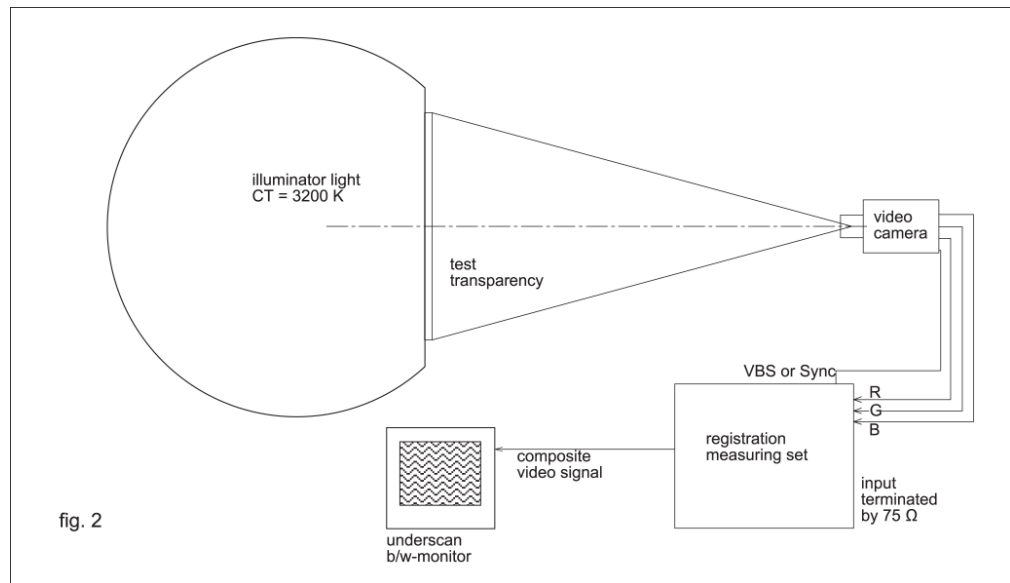
## TRANSPARENCY



The TE179 is designed to measure registration of video cameras.  
The circuit arrangement of the measurement shall be as shown in fig. 2.

### If light is possible the conditions of shooting shall be as follows

- The light density of the transparency version shall be  $939 \text{ cd/m}^2 \pm 5\%$  (=2000 lx) at peak white
  - The correlated color temperature of the light source shall be  $3200 \text{ K} \pm 100 \text{ K}$
  - The white balance shall be set manually or automatically to  $3200 \text{ K} \pm 100 \text{ K}$
  - The test chart shall be shot by the camera so that the frame limited by the arrows exactly coincides with the edges of the picture displayed on the monitor in underscan mode
  - The focus control shall be in auto or manual mode and shall be in best focus
  - The iris control shall be in auto or manual mode
  - Black level corrector „ON“
  - Flare corrector „ON“
  - Black balanced with lens capped at 35mV level
  - White balanced using the illuminator with 100% white chart at  $382 \text{ cd/m}^2$  (= 1200 lx)
  - Color matrixing corrector „OFF“
  - Contour corrector „OFF“
  - Noise reducer „OFF“
  - Aperture corrector „OFF“
  - Black and white shading corrector „ON“ and optimized
  - Gamma corrector set to „1“
  - Gain control shall be set to „0 dB“
  - Optical filter, if any, shall be set to „open“ position
- 
- The iris shall be adjusted to attain the G-channel signal level of 70% of the nominal signal level.
  - A horizontal line which crosses each “V” mark shall be selected and timing offsets against G-channel signal, a, a'-b, b', as shown in fig. 3, shall be measured of R-channel and B-channel signals, respectively



Horizontal and vertical displacements,  $\Delta H$  and  $\Delta V$ , shall be calculated by the following equations

$$\Delta H = (A+B) / 2$$

$$\Delta V = (A-B) / 2$$

$$\text{where } A = (a+a') / 2 \text{ and } B = (b+b') / 2$$

This measurements shall be conducted for each five horizontal lines which cross over the marks.

Horizontal and vertical registration errors,  $R_H$ ,  $R_V$ , shall be calculated as in:

$$R_H = (\Delta H/H_r) \times (4/3)$$

$$R_V = (\Delta V/H_r) \times (4/3)$$

where  $H_r$  is the horizontal sweep time

### Presentation of the results

The maximum horizontal and vertical registratin errors  $R_{Hmax}$ ,  $R_{Vmax}$  in precentage shall be reported together with teir positions as in column number-row number. The minus signal shall precede the reported figures in case that R-channel and B-channel signal lead the G-channel signal. The plus sign shall be applied for the opposite case, as exemplified for the case depicted in fig.3.

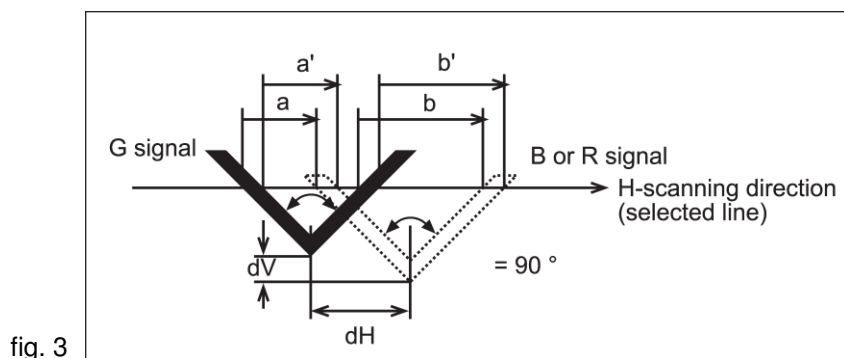
$$R_{Hmax} = + 0,12 \% \text{ at } 1 - 5$$

$$R_{Vmax} = + 0,11 \% \text{ at } 5 - 1$$

The specification of the lens and its focal length shall also be reported.



### Extraction of registration errors



The segments  $a$ ,  $a'$ ,  $b$ ,  $b'$  shall be considered as vectors whose origins are the crossing points of the selected line with „V“ marks of the G-channel taken as reference is  $c$  for  $a$ ,  $d$  for  $a'$ ,  $e$  for  $b$ , and  $f$  for  $b'$  as exemplified in fig. 3. As to sign of  $a$ ,  $a'$ ,  $b$  and  $b'$ , the direction of the horizontal scanning is taken to be positive.